Name (Print)

I understand that cheating is a serious offense.

Signature:

Student Number

THE UNIVERSITY OF MANITOBA DEPARTMENT OF MATHEMATICS 136.130 Vector Geometry and

Linear Algebra Mid-Term Exam

Date: Friday, October 26, 2001 Time: 5:30–6:30 PM

		DO NOT WRITE			
Section	Instructor	Slot	Time	Room	IN THIS COLUMN
L01	C R Platt	2	MWF 9:30–10:20	224 Engin.	1 /
L02	S Kalajdzievski	8	MWF 1:30-2:20	221 Wallace	Total /0
L03	B E Stebnicky	8	MWF 1:30-2:30	225 St. Paul's	
L04	C K Gupta	9	TT 11:30-1:00	204 Armes	
Other	(SJR, deferred, etc.)				

Instructions

Give the required information above, including your printed name, your student number, and your signature. An exam without a signature could be declared unacceptable!

This is a one-hour exam.

No calculators, texts, notes, or other aids are permitted.

Show your work clearly for full marks.

This exam has 0 questions on 0 pages, for a total of 0 points. *Check now* that you have a complete exam.

There are two extra blank pages at the end for rough work. **Do not** separate the pages.

Answer all questions on the exam paper in the space provided. If you need more room, you may continue your answer on the reverse side, but algorith indicate that your work is continued there

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 TIME: 1 HOUR

 EXAMINER: Gupta, Kalajdzievski, Platt, Stebnicky

[Values] [10]

1. Let $\mathbf{u} = (1, -2, 0)$, $\mathbf{v} = (3, 0, -2)$, $\mathbf{w} = (3, 4, -6)$, $\mathbf{p} = (2, 4, -2, 0)$, and $\mathbf{q} = (1, 0, -1, 1)$.

Calculate each of the following.

(a) 2u + 3(v - 2u)

$$2\mathbf{u} + 3(\mathbf{v} - 2\mathbf{u}) = (5, 8, -6)$$

(b) $(\mathbf{p} \bullet \mathbf{q})\mathbf{v} \times \mathbf{u}$

$$(\mathbf{p} \cdot \mathbf{q})\mathbf{v} \times \mathbf{u} = 4 \cdot (-4, -2, -6) = (-16, -8, -24)$$

(c) The unit vector with the same direction as q.

$$\frac{(1,0,-1,1)}{\sqrt{1+0+1+1}} = \frac{(1,0,-1,1)}{\sqrt{3}}$$

(d) The cosine of the angle between u and w

$$\cos \theta = \frac{\mathbf{u} \cdot \mathbf{w}}{||\mathbf{u}|| \, ||\mathbf{v}||} = \frac{-5}{\sqrt{5}\sqrt{51}}$$

(e) The angle between u and $w \times u$.

 $\mathbf{w} \times \mathbf{u}$ is perpendicular to \mathbf{u} . So the angle between the two is $\frac{\pi}{2}$.

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[Values] [15]

2.

(a) Let L be the line containing point Q(1, 1, 0) and which is parallel to $\mathbf{v} = (1, 1, 3)$. Find parametric equations for the line L.

The parametric equations can be read straight from what we are given.

$$x = 1 + t$$
$$y = 1 + t$$
$$z = 3t$$

(b) Find the point of intersection of the line L of part (a) with the plane Π whose equation is 3x + 2y + z = 2.

Solve the system defined by the three equations from (a) and the one defining the plane. Get (with $t = -\frac{3}{8}$) $x = \frac{5}{8}$, $y = \frac{5}{8}$ and $z = -\frac{9}{8}$. So, the intersection point is $(\frac{5}{8}, \frac{5}{8}, -\frac{9}{8})$.

(c) Find an equation in standard form of the plane containing the points P(-1, 2, 1), Q(1, 1, 0), and the origin, (0, 0, 0).

 $\mathbf{n} = (-1, 2, 1) \times (1, 1, 0) = (-1, 1, -3)$ is a vector perpendicular to the plane. So, the point normal equation of the plane is

$$((x, y, z) - (1, 1, 0)) \cdot (-1, 1, -3) = 0.$$

After expanding we get the equation in standard form:

$$-x + y - 3z = 0.$$

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[Values]			$3x_1$	+	$3x_2$	+	$6x_2$	=	3
[40]	3. Given the system	Given the system	$2x_1$	+	x_2	_	x_3	=	3
[12]				_	x_2	_	$5x_3$	=	1
			$-5x_{1}$	_	$2x_2$	+	$5x_3$	=	-8

(a) Write the augmented matrix of this system.

3	3	6		3
2	1	-1		3
0	-1	-5	Ì	1
-5	-2	5		-8_{-}

(b) Convert the augmented matrix into reduced row echelon form using elementary row operations. Specify which operations you are using.

The row reduced echelon form of the augmented matrix is

[1	0	-3	2
0	1	5	-1
0	0	0	0 .
0	0	0	0

(c) Give the general solution of the system, using parameters where necessary.

Set $x_3 = t$ to get $x_1 = 2 + 3t$ and $x_2 = -1 - 5t$. So, the general solution is $(x_1, x_2, x_3) = (2 + 3t, -1 - 5t, t)$.

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 [Values]

 [10]
 4. Let

$$A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 6 & 2 \\ 3 & 3 & 1 \end{bmatrix}, \quad C = \begin{bmatrix} -4 & -1 \\ 3 & 0 \\ 1 & 2 \end{bmatrix}, \quad D = \begin{bmatrix} 1 & 2 \\ -2 & 0 \end{bmatrix}$$

For each expression, **first** determine **whether it is defined**. If so, simply answer "Yes." If it is not defined, state the reason why not (answer "No, because ... "). You should be able to do this part without doing any calculation.

Then, If the expression *is* defined, evaluate it. (Note: In some cases, you can use rules for matrix algebra to simplify the expression, or even to determine the answer without calculation.)

(a) DA - AD

$$DA - AD = \begin{bmatrix} 2 & -1 \\ -2 & -2 \end{bmatrix}$$

(b) $(AD)^{T} - D^{T}A^{T}$

By a property linking transpose with matrix multiplication the result is $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$. (c) BC - CB

This is not defined: BC is a 2 by 2 matrix, while CB is 3 by 3 matrix. (d) $3A^T + BC$

$$3A^T + BC = 3\begin{bmatrix} 2 & 0\\ 1 & 1 \end{bmatrix} + \begin{bmatrix} 12 & 2\\ -2 & -1 \end{bmatrix} = \begin{bmatrix} 18 & 2\\ 1 & 2 \end{bmatrix}.$$

Friday, October 26, 2001, 5:30-6:30 PM Mid-Term Exam PAGE NO: 5 of 0 COURSE: Mathematics 136.130 Vector Geometry and Linear Algebra TIME: 1 HOUR EXAMINER: Gupta, Kalajdzievski, Platt, Stebnicky [Values] 5. [13] (a) Find the inverse matrix A^{-1} of the matrix $A = \begin{bmatrix} 1 & 0 & 1 \\ -2 & 1 & -2 \\ 1 & 4 & 0 \end{bmatrix}$, and verify your answer by matrix multiplication. The row reduction technique yields $A^{-1} = \begin{bmatrix} -8 & -4 & 1 \\ 2 & 1 & 0 \\ 9 & 4 & -1 \end{bmatrix}$. To check the answer we multiply $A \cdot A^{-1}$ and see if the result is the identity matrix of size 3. (**b**) Let $\mathbf{p} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ and $\mathbf{q} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$. By using A^{-1} , find the solution to $A\mathbf{x} = \mathbf{p}$, and the solution to $A\mathbf{x} = \mathbf{q}$, where A and \bar{A}^{-1} are as in part (a). No other methods may be used; no points will be given if A^{-1} is not made use of (meaningfully). The solution of $A\mathbf{x} = \mathbf{p}$ is $\mathbf{x} = A^{-1}\mathbf{p} = \begin{bmatrix} -12\\3\\13 \end{bmatrix}$ The solution of $A\mathbf{x} = \mathbf{q}$ is $\mathbf{x} = A^{-1}\mathbf{q} = \begin{bmatrix} -3\\1\\3 \end{bmatrix}$