

## Eigenvalues And Eigenvectors: Diagonalization

**Recall:** If  $A \in M_{n \times n}(\mathbb{F})$  then the characteristic polynomial of  $A$  is  $\Delta(\lambda) = \det(A - \lambda I_n)$  which is a polynomial in  $\lambda$ .

**Proposition:** Let  $A \in M_{n \times n}(\mathbb{F})$ . The eigenvalues of  $A$  are the roots of the characteristic polynomial of  $A$  (i.e., the values of  $\lambda$  such that  $\det(A - \lambda I_n) = 0$ ).

**Corollary:** If  $A \in M_{n \times n}(\mathbb{F})$  then  $\det(A)$  is the product of its eigenvalues.

**Proposition:** Let  $A \in M_{n \times n}(\mathbb{F})$  and let  $\lambda$  be an eigenvalue of  $A$ . The eigenspace  $E_\lambda$  corresponding to  $\lambda$  is  $\text{Null}(A - \lambda I_n)$ .

**Example:** Let

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}.$$



## Some Facts About Characteristic Polynomials

Some important facts about characteristic polynomials follow from the following fundamental theorem.

**Fundamental Theorem of Algebra/Definition:** Every degree  $n$  polynomial factors as

$$a(x - c_1)^{k_1}(x - c_2)^{k_2} \cdots (x - c_m)^{k_m}$$

where  $c_1, \dots, c_m \in \mathbb{C}$  are distinct,  $k_1 + k_2 + \cdots + k_m = n$ , and  $0 \neq a \in \mathbb{C}$ . The  $c_i$  are called the **roots** of the polynomial and  $k_i$  is called the **algebraic multiplicity** of the root  $c_i$ .

**Fact:** If  $A \in M_{n \times n}(\mathbb{F})$  then the characteristic polynomial of  $A$  is a polynomial of degree  $n$ .

So...when counted correctly,  $A \in M_{n \times n}(\mathbb{F})$  has exactly  $n$  eigenvalues.

**Example:** The matrix  $A$  from the previous example has size  $3 \times 3$  and has 3 eigenvalues (counted correctly):

## Diagonalization

Recall that we want diagonal matrices for our matrix representations!

**An Old Example:** Consider the linear transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  given by

$$T \left( \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right) = \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \frac{2(x + y + z)}{3} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}.$$

We use the two bases for  $\mathbb{R}^3$ :

- $\mathcal{B}$  is the standard basis
- $\mathcal{C} = \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right\}.$

Then

$$[T]_{\mathcal{B}}^{\mathcal{B}} = \begin{bmatrix} 1/3 & -2/3 & -2/3 \\ -2/3 & 1/3 & -2/3 \\ -2/3 & -2/3 & 1/3 \end{bmatrix} \quad \text{and} \quad [T]_{\mathcal{C}}^{\mathcal{C}} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Moreover,

**Definition:** A square matrix  $A$  is said to be **diagonalizable** if there exists an invertible matrix  $P$  such that

**Definition:** Two matrices  $A$  and  $B$  in  $M_{n \times n}(\mathbb{F})$  are said to be **similar** if

**Theorem:** If  $A$  and  $B$  are similar matrices, then they have the same determinant, same eigenvalues, same rank, and same trace.

