

## Chapter 1: Linear Equations in Linear Algebra

### Section 1.8 – Introduction to Linear Transformations (Continued)

**Matrix Transformations:** Let  $A$  be an  $m \times n$  matrix. We can define the transformation  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  by  $T(\mathbf{x}) = A\mathbf{x}$  for each  $\mathbf{x}$  in  $\mathbb{R}^n$ . Note

**Examples:**

1. Let  $A = \begin{bmatrix} 1 & -4 & 2 & -1 \\ -2 & 6 & 4 & -1 \end{bmatrix}$ . Define  $T : \mathbb{R}^4 \rightarrow \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Thus,

(a) Let  $\mathbf{u} = \begin{bmatrix} -1 \\ 2 \\ 0 \\ 1 \end{bmatrix}$ . Find  $T(\mathbf{u})$ .

(b) Let  $\mathbf{b} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ . Find  $\mathbf{x}$  in  $\mathbb{R}^4$  such that  $T(\mathbf{x}) = \mathbf{b}$ . Is  $\mathbf{x}$  unique?

2. Define  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$  where  $A = \begin{bmatrix} 2 & -3 \\ -6 & 9 \end{bmatrix}$ . Let  $\mathbf{y} = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$ . Is  $\mathbf{y}$  in the range of  $T$ ?

We now consider special transformations!

**Example:** Define  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  by  $T(\mathbf{x}) = A\mathbf{x}$  where  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ . Thus,

$$T \left( \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ 0 \end{bmatrix}.$$

**Definition:** A transformation  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is called **linear** if

**Examples:**

1. Consider  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  given by  $T(\mathbf{x}) = 2\mathbf{x}$ .

2. Let  $A$  be an  $m \times n$  matrix. Define  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Then for all  $\mathbf{x}, \mathbf{y}$  in  $\mathbb{R}^n$  and scalars  $c$  we have

**Properties:** Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation.

**Examples:**

1.  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  given by  $T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 3|x_1| \\ x_1 + x_2 \end{bmatrix}$  is not linear

2. Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be reflection through  $x_2 = 0$ :

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 \\ -x_2 \end{bmatrix}.$$

Let  $c, d$  be scalars and  $\mathbf{x}, \mathbf{y}$  be in  $\mathbb{R}^2$ .

3. Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a linear transformation such that

$$T \left( \begin{bmatrix} 5 \\ 5 \end{bmatrix} \right) = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \text{and} \quad T \left( \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

What is  $T \left( \begin{bmatrix} 3 \\ 1 \end{bmatrix} \right)$ ?