A multi-species epidemic model with spatial dynamics

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Abstract

A model is formulated that describes the spatial propagation of a disease that can be transmitted between multiple species. The spatial component consists, for each species, of a certain number of patches that make up the vertices of a digraph, the arcs of which represent the movement of the various species between the patches. In each of the patches and for each species, an SEIR model describes the evolution of the disease status of individuals. Also in each patch, there is transmission of the disease from species to species. An analysis of the system is given, beginning with results on the mobility component. A formula is derived for the computation of the basic reproduction number $R_0$ for $s$ species and $n$ patches, which then determines the global stability properties of the disease free equilibrium. Simulations for the spread of a disease in 1 species and 2 patches are presented.

1 Introduction

The spatial and temporal spread of infectious diseases is of considerable practical importance. The world has observed the efficient spatial spread of infection fol-
ollowing the introduction of agents at discrete locations and times; plague in Europe in the 1300s, smallpox in the New World in the 1500s [Zinsser, 1935], West Nile virus in North America in the 1990s [Petersen and Roehrig, 2001], and SARS in Asia in 2003 [World Health Organization, 2003] are but a few examples. Concern over potential biological terrorism [Henderson, 1999] further highlights the need to understand the dynamics of disease outbreaks. To the extent that population and geographic heterogeneities play key roles in the infection-spread process, epidemiology models must include them, in order to capture the necessary character of the epidemic and endemic states. Population heterogeneities, such as age structure, multiple risk groups, and the existence of vector species are routinely handled in models, see, for example, [Grenfell and Dobson, 1995, Isham and Medley, 1996, Mollison, 1995]. However, much of classical mathematical epidemiology tends to minimize geographic heterogeneity and related spatial aspects of deterministic epidemic models.

One notable example of a deterministic disease model that includes spatial heterogeneity is provided by the work of Baroyan et al., which is applied to the spatial spread of influenza between cities in the Soviet Union [Baroyan and Rvachev, 1967, Baroyan et al., 1971]. In their approach, a large geographic region (country) is partitioned into smaller sub-regions (cities). Migration and transportation between these sub-regions are explicitly incorporated. Within a given sub-region, transmission is handled according to a discrete deterministic compartmental SIR model. The spread of infection from city to city could be modeled, given appropriate transportation data. Such an approach is appealing because it allows infection to be modeled on single-patch, as well as multi-patch scales, preserving patch-to-patch heterogeneity. A general compartmental model can be formulated and applied on a patch-by-patch basis, allowing for variations in population and immunological attributes. If information on the flow of individuals between patches is known, or if reasonable estimates can be made, then the spread of contagion between patches can be investigated.

Theoretical analysis of such migration models has until recently been confined to limiting cases, wherein the model reduced to the more familiar reaction-diffusion formulation [Murray, 1993]. Models with a multi-patch formulation have recently been considered by [Sattenspiel and Dietz, 1995, Arino and van den Driessche, 2003, Wang and Zhao, 2004]. The desirability of having analytic, as opposed to purely numerical, tools to analyze this class of multi-patch models is evident: such tools should allow for valuable predictions and analysis of the behavior of solutions for the model. For example, it is desirable to be able to determine the linear stability of the disease free equilibrium (i.e., compute the basic reproduction number $R_0$) explicitly in terms of model parameters. Similarly, a detailed theoretical analysis can be expected to suggest whether migration between arbitrary patches tends to have a stabilizing or a destabilizing effect.

We undertake such a theoretical analysis of a general multi-species, multi-patch model with four disease status compartments (an SEIR model). In Section 2, the model is described, in Section 3 it is analyzed and a general formula for $R_0$ is derived; a proof of the global stability of the disease free equilibrium in the case $R_0 < 1$ is given. In Section 4, we consider the case of a single species on multiple
patches, including numerical simulations of the spread of disease concentrating on the case of two patches.

2 The model

An SEIR epidemic model with spatial dynamics is considered for a population consisting of \( s \) species and occupying \( n \) spatial patches. The numbers of susceptible, latent, infective (infectious) and recovered individuals of species \( i \) in patch \( p \) at time \( t \) are denoted by \( S_{ip} \), \( E_{ip} \), \( I_{ip} \) and \( R_{ip} \), respectively, with the total number of individuals of species \( i \) in patch \( p \) denoted by \( N_{ip} \). Note that, unlike the single species models introduced by [Sattenspiel and Dietz, 1995] and further analyzed by [Arino and van den Driessche, 2003], we do not keep track of where an individual usually resides, but only where an individual is at time \( t \). The dynamics for species \( i = 1, \ldots, s \) in patch \( p = 1, \ldots, n \) is given by the following system of \( 4sn \) equations;

\[
\frac{dS_{ip}}{dt} = d_{ip}(N_{ip} - S_{ip}) - \sum_{j=1}^{s} \beta_{ijp} S_{ip} \frac{I_{jp}}{N_{jp}} + \sum_{q=1}^{n} m_{ipq} S_{iq} - \sum_{q=1}^{n} m_{iqp} S_{ip} \quad (2.1a)
\]

\[
\frac{dE_{ip}}{dt} = \sum_{j=1}^{s} \beta_{ijp} S_{ip} \frac{I_{jp}}{N_{jp}} - (d_{ip} + \varepsilon_{ip}) E_{ip} + \sum_{q=1}^{n} m_{ipq} E_{iq} - \sum_{q=1}^{n} m_{iqp} E_{ip} \quad (2.1b)
\]

\[
\frac{dI_{ip}}{dt} = \varepsilon_{ip} E_{ip} - (d_{ip} + \gamma_{ip}) I_{ip} + \sum_{q=1}^{n} m_{ipq} I_{iq} - \sum_{q=1}^{n} m_{iqp} I_{ip} \quad (2.1c)
\]

\[
\frac{dR_{ip}}{dt} = \gamma_{ip} I_{ip} - d_{ip} R_{ip} + \sum_{q=1}^{n} m_{ipq} R_{iq} - \sum_{q=1}^{n} m_{iqp} R_{ip} \quad (2.1d)
\]

where \( N_{ip} = S_{ip} + E_{ip} + I_{ip} + R_{ip} \). Here \( 1/d_{ip} > 0 \), \( 1/\varepsilon_{ip} > 0 \), \( 1/\gamma_{ip} > 0 \) are the average lifetime, latent period and infectious period for species \( i \) in patch \( p \), respectively. All newborns are assumed to be susceptible with birth term \( d_{ip}N_{ip} \), and disease related mortality is neglected. The disease is assumed to be horizontally transmitted within and between species according to standard incidence (see, e.g., [Hethcote, 2000, McCallum et al., 2001]) with \( \beta_{ijp} \geq 0 \) the rate of disease transfer from species \( j \) to species \( i \) in patch \( p \). The rate of travel, for species \( i \), from patch \( q \) to patch \( p \), is given by \( m_{ipq} \) with \( m_{ipq} \geq 0 \) and is assumed to be the same for each type of individual of species \( i \). We set \( m_{ipp} = 0 \), but note that the \( m_{ipp} \) terms cancel in each equation. We use the terms movement, travel, migration and mobility interchangeably throughout the text. The population of species \( i \) in patch \( p \) is \( N_{ip} \), and the total population for species \( i \) is \( \sum_{p=1}^{n} N_{ip} = N_{i}^0 \), a fixed constant. The initial value problem is given by (2.1) together with initial conditions \( N_{ip} > 0 \) and \( S_{ip}, E_{ip}, I_{ip}, R_{ip} \geq 0 \) at time \( t = 0 \). The system (2.1) is well posed, with all variables remaining nonnegative and \( N_{ip} \) positive for \( t \geq 0 \).

By adding the equations in (2.1), the mobility equation for the population of
species $i$ in patch $p$ is
\[
\frac{dN_{ip}}{dt} = \sum_{q=1}^{n} m_{ipq}N_{iq} - \sum_{q=1}^{n} m_{ipq}N_{ip}
\] (2.2)

With $N_i = [N_{i1}, \ldots, N_{in}]^t$, this can be written as the linear system
\[
\frac{dN_i}{dt} = M_iN_i
\] (2.3)

with mobility matrix for species $i$
\[
M_i = \begin{bmatrix}
-\sum_{q=1}^{n} m_{i1q} & m_{i21} & \cdots & m_{i1n} \\
\vdots & \ddots & \ddots & \vdots \\
m_{in1} & m_{in2} & \cdots & -\sum_{q=1}^{n} m_{inq}
\end{bmatrix}
\] (2.4)

Note that $(-M_i)$ has the Z-sign pattern and (since there are no birth and death during travel) each column sum of $M_i$ is zero, i.e., $1^t_n (-M_i) = 0$ for all $i$, where the $1 \times n$ vector $1^t_n = [1, \ldots, 1]$. Thus $(-M_i)$ is a singular M-matrix; see, e.g., [Fiedler, 1986, Th. 5.11].

The zero/nonzero structure of the mobility matrix $M_i$ specifies the arcs of a directed graph (digraph) describing how the patches as vertices are connected. For species $i$, a patch $q$ has direct access to patch $p$ [Berman and Plemmons, 1979, p. 39] if $m_{ipq} > 0$ (i.e., $qp$ is an arc in the digraph). Patch $q$ has an access to patch $p$ if there exists a path in the digraph from $q$ to $p$. Patch $q$ has an access to patch $p$ for all $p, q$ if and only if $M_i$ is irreducible.

3 Analysis of the general model

System (2.1) is at an equilibrium if all time derivatives are zero. There is no disease in species $i$ if $E_{ip} = I_{ip} = 0$ for $p = 1, \ldots, n$. Similarly there is no disease in patch $p$ if $E_{ip} = I_{ip} = 0$ for $i = 1, \ldots, s$. If patch $p$ is at an equilibrium and has no disease, then it is at the disease free equilibrium (DFE). The system is at the DFE if $E_{ip} = I_{ip} = 0$ for all $i, p$. From (2.1d) with $I_{ip} = 0$ and $R_i = (R_{i1}, \ldots, R_{in})^t$, it follows that $dR_i/dt = (M_i - \text{diag}(d_{i1}, \ldots, d_{in}))R_i$. The matrix $M_i - \text{diag}(d_{i1}, \ldots, d_{in})$ is nonsingular, implying that at the DFE, $R_i = 0$, and so $S_{ip} = N_{ip}^*$, where $N_{ip}^*$ is a constant. The disease in patch $p$ is at an endemic equilibrium in species $i$ if $E_{ip} + I_{ip} > 0$ for some $i$.

The graph theoretic ideas introduced above are used in the following two results; in particular, to determine where the endemic equilibrium in one patch propagates by mobility.

**Theorem 3.1.** Suppose that system (2.1) is at an equilibrium and that there is no disease in patch $p$. Then for a given species $i$, $E_{ij} = I_{ij} = 0$ for each patch $j$ that has an access to patch $p$. In particular, if the matrices $M_i$ are irreducible, then the system is at the disease free equilibrium.
Proof. Fix the species index at \( i \). For simplicity suppose that \( p = 1 \), \( i.e. \), that there is no disease in patch 1, thus \( E_{i1} = I_{i1} = 0 \). Then for \( p = 1 \), (2.1c) is

\[
0 = \frac{dI_{i1}}{dt} = \sum_{r=2}^{n} m_{i1r} I_{ir}
\]

For a given patch \( r \) define

\[
T_{da}^r = \{ q : m_{irq} > 0 \}
\]

as the subset of patches with a direct access to patch \( r \), and

\[
T_{nda}^r = \{ q \neq r : m_{irq} = 0 \}
\]

as the subset of patches with no direct access to \( r \). Using these subsets of indices for patch 1, it follows from the nonnegativity of \( I_{ir} \) and

\[
\sum_{r=2}^{n} m_{i1r} I_{ir} = \sum_{r \in T_{da}^1} m_{i1r} I_{ir} + \sum_{r \in T_{nda}^1} m_{i1r} I_{ir} = 0
\]

that \( I_{ir} = 0 \) for \( r \in T_{da}^1 \). Similarly, setting \( p = 1 \) in (2.1b) and using \( T_{da}^1 \) it follows that \( E_{ir} = 0 \) for \( r \in T_{da}^1 \). Thus all patches \( r \) with a direct access to patch 1 have no disease, \( i.e. \), are such that \( E_{ir} = I_{ir} = 0 \).

Now consider a patch \( r \) in \( T_{da}^1 \). Using the same argument as previously, it follows that \( E_{iw} = I_{iw} = 0 \) for all \( w \in T_{da}^1 \). Patches that are in \( T_{da}^1 \ \setminus T_{da}^1 \) have a length 2 access to patch 1. By induction, all patches belonging to the same strongly connected component of the digraph as patch 1, are at the DFE if patch 1 is at the DFE.

A sufficient condition for all patches to be disease free (if one patch is disease free) is for \( M_i \) to be irreducible. If \( M_i \) is reducible, then all patches belonging to the strongly connected component of patch 1 are at the DFE.

Theorem 3.2. Suppose that system (2.1) is at an equilibrium. If the disease in patch \( p \) is at an endemic equilibrium in species \( i \), then the disease is also at an endemic equilibrium in species \( i \) in all patches to which patch \( p \) has an access. In particular, if matrix \( M_i \) is irreducible, then the disease is at an endemic equilibrium in species \( i \) in all patches.

Proof. Fix the species index \( i \). For simplicity suppose that \( p = 1 \), \( i.e. \), \( E_{i1} + I_{i1} > 0 \). From (2.1b) and (2.1c) with \( q \neq 1 \),

\[
0 = \frac{d}{dt}(E_{iq} + I_{iq}) = \sum_{j=1}^{s} \beta_{ijq} S_{ij} \frac{I_{iq}}{N_{iq}} - d_{iq}(E_{iq} + I_{iq}) - \gamma_{iq} I_{iq}
\]

\[
+ \sum_{r=1}^{n} m_{iqr}(E_{ir} + I_{ir}) - \sum_{r=1}^{n} m_{irq}(E_{iq} + I_{iq})
\]

Assume that \( E_{iq} + I_{iq} = 0 \) (\( i.e. \), \( E_{iq} = I_{iq} = 0 \)) and \( m_{iq1} > 0 \), \( i.e. \), patch 1 has access to patch \( q \). Then equation (3.1) reduces to

\[
0 = \sum_{r=1}^{n} m_{iqr}(E_{ir} + I_{ir})
\]
and implies that $E_{i1} + I_{i1} = 0$, giving a contradiction. Thus the disease in patch $q$ is at an endemic equilibrium. The remainder of the proof follows as in the proof of Theorem 3.1.

We now assume that matrix $M_i$ is irreducible for each species $i$; that is, there exists a path in the digraph from patch $q$ to patch $p$ for all $p, q$.

**Theorem 3.3.** *The mobility equation (2.3) subject to the constraint of constant total population for species $i$ has a positive equilibrium, which is asymptotically stable.*

**Proof.** Without loss of generality, the species index $i$ can be dropped. Finding the equilibrium amounts to solving the $n + 1$ linear equations in $n$ variables

$$
\begin{bmatrix}
\mathbb{I}_n \\
M
\end{bmatrix}
\begin{bmatrix}
N_1 \\
N_2 \\
\vdots \\
N_n
\end{bmatrix}
= 
\begin{bmatrix}
N^0 \\
0 \\
\vdots \\
0
\end{bmatrix}
$$

(3.1)

All column sums of the last $n$ rows are zero, thus the second equation (for example) can be eliminated. Now perform column operations $c_r \leftarrow c_r - c_1$ for $r = 2, \ldots, n$ on the determinant of the resulting coefficient matrix, reducing it to the $n - 1$ determinant

$$
\det(-M(1)) = \det(M(1) + T_1)
$$

where $M(1)$ denotes matrix $M$ with its first row and column deleted, thus

$$
M(1) = \begin{bmatrix}
- \sum_{q=1}^n m_{q1} & m_{23} & \cdots & m_{2n} \\
\vdots & \ddots & \ddots & \vdots \\
m_{n2} & m_{n3} & \cdots & - \sum_{q=1}^n m_{nq}
\end{bmatrix}
$$

and $T_1 = m_1 \mathbb{I}_{n-1} = [\ldots, -m_{n1}]^t [1, \ldots, 1]$, where $m_1$ is the vector formed from the first column of $M$ by omitting the first entry.

By [Berman and Plemmons, 1979, M35, p. 127] since $m_{pq} \geq 0$, $-M(1)$ is a nonsingular M-matrix (it has the Z-sign pattern and $\mathbb{I}_{n-1} (-M(1)) \geq 0$ and is not the zero vector by the assumption that $M$ is irreducible). Thus $\det(-M(1)) > 0$ and so $\det(M(1))$ has sign $(-1)^{n+1}$. Since $T_1$ has rank 1, it follows from the linearity of the determinant subject to rank 1 perturbations, see, e.g., [Rump, 1997, Corollary 4.2], that $\det(M(1) + T_1) = \det(M(1)(1 + \mathbb{I}_{n-1} M(1)^{-1} m_1))$. As $-M(1)$ is an M-matrix, $(-M(1)^{-1}) \geq 0$, thus $M(1)^{-1} \leq 0$. But $m_1 \leq 0$, thus $1 + \mathbb{I}_{n-1} M(1)^{-1} m_1$ is positive and so $\det(M(1) + T_1)$ has the sign of $\det(M(1)$, namely $(-1)^{n+1}$.

By Cramer’s Rule,

$$
N_1 = \frac{\det(M(1)N^0}{\det(M(1) + T_1)} = \frac{N^0}{1 + \mathbb{I}_{n-1} M(1)^{-1} m_1} > 0
$$

Similarly by deleting the $(p + 1)^{st}$ equation in (3.1),

$$
N_p = \frac{\det(M(p)N^0}{\det(M(p) + T_p)} = \frac{N^0}{1 + \mathbb{I}_{n-1} M(p)^{-1} m_p} > 0
$$
where \( T_p = m_p \mathbb{I}_{n-1} = [-m_{1p}, \ldots, -m_{p-1,p}, -m_{p+1,p}, \ldots, -m_{np}]^t \mathbb{I}_{n-1} \) for \( p = 1, \ldots, n \). Here \( m_p \) is the vector formed from the \( p \)th column of \( M \) by omitting the \( p \)th entry. Thus given a value of \( N^0 \), there is a unique positive solution \( N_p = N^*_p \) for \( p = 1, \ldots, n \).

Since \((-M)\) is an irreducible singular M-matrix, 0 is a simple eigenvalue and all the nonzero eigenvalues of \( M \) have negative real parts. The zero eigenvalue occurs as a consequence of the constant population constraint. Thus the population \( N^*_p \) in each patch tends to \( N^*_p \).

From the above result, the DFE for species \( i \) in patch \( p \) exists with \( \hat{S}_{ip} = N^*_i \).

Note that \( N^*_i = (N^*_{i1}, \ldots, N^*_{in})^t \) is a right nullvector of \( M_i \). An example for 3 species on 2 patches is given below in Section 3.1.

The local stability of the DFE of system (2.1) is governed by the basic reproduction number \( R_0 \), which depends in general on the demographic, disease and mobility parameters. A formula for the basic reproduction number \( R_0 \) for system (2.1) is derived using the next generation matrix ([Diekmann and Heesterbeek, 2000] and [van den Driessche and Watmough, 2002]) and can be used to determine numerically the value of \( R_0 \) for a given set of parameter values. This method involves writing the flows of individuals between the different compartments as two vectors \( F \) and \( V \). The former describes the inflow of new infected individuals, hence here corresponds to the infection terms for each exposed class. The vector \( V \) then summarizes all other flows occurring in the system. Differentiating with respect to the state variables, keeping only those parts of \( DF \) and \( DV \) relative to the infected classes (i.e., \( E_{ip} \) and \( I_{ip} \) here), and evaluating at the DFE gives matrices \( F \) and \( V \). The value of \( R_0 \) can be deduced as \( R_0 = \rho(FV^{-1}) \), where \( \rho \) is the spectral radius. The basic reproduction number acts as a threshold for stability of the DFE; if \( R_0 < 1 \) then the DFE is locally asymptotically stable (all eigenvalues of \( F - V \) have negative real parts), whereas it is unstable if \( R_0 > 1 \) [van den Driessche and Watmough, 2002, Theorem 2].

To determine the matrices \( F \) and \( V \), order the state variables by type, then by patch, i.e.,

\[
E_{11}, E_{21}, \ldots, E_{s1}, E_{12}, \ldots, E_{sn}, I_{11}, I_{21}, \ldots, I_{s1}, I_{12}, \ldots, I_{sn}.
\]

Then the nonnegative matrix \( F \) has the form

\[
F = \begin{bmatrix}
0 \oplus G_k \\
\end{bmatrix} = \begin{bmatrix}
0 \\
\end{bmatrix}
\]

\[
\begin{bmatrix}
0 \\
\end{bmatrix}
\]

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and the matrix $V$ is the block matrix

$$V = \begin{bmatrix} A & 0 \\ -C & B \end{bmatrix} = \begin{bmatrix} \begin{bmatrix} A_{11} & \cdots & A_{1n} \\ \vdots & \ddots & \vdots \\ A_{n1} & \cdots & A_{nn} \end{bmatrix} & 0 \\ \begin{bmatrix} \sum_{k=1}^{n} C_k \\ \vdots \\ \vdots \\ \sum_{k=1}^{n} C_n \end{bmatrix} & \begin{bmatrix} B_{11} & \cdots & B_{1n} \\ \vdots & \ddots & \vdots \\ B_{n1} & \cdots & B_{nn} \end{bmatrix} \end{bmatrix}$$

Here $G_k$ is an $s \times s$-matrix with $(i, j)$ entry equal to $\beta_{ijk} N_{ik}^* / N_{jk}^*$. Matrix $A$ is the block matrix $A = A_{jk}$, with each $A_{jk}$ block an $s \times s$ diagonal matrix. The $(i, i)$ entry of $A_{kk}$ is equal to $d_{ik} + \epsilon_{ik} + \sum_{l=1}^{n} m_{ikl}$, whereas for $j \neq k$ the $(i, i)$ entry of $A_{jk}$ is $-m_{ijk}$. Matrix $B$ is the same as $A$ but with $\epsilon_{ik}$ replaced by $\gamma_{ik}$. Finally, $C_k$ is an $s \times s$ diagonal matrix with $(i, i)$ entry equal to $\epsilon_{ik}$.

Matrices $G$, $A$, $B$ and $C$ are $sn \times sn$-matrices. Matrices $A$ and $B$ are nonsingular $M$-matrices since they have the Z-sign pattern and are diagonally dominant by columns [Berman and Plemmons, 1979, M35 p. 127]. Thus $A^{-1}$ and $B^{-1}$ are nonnegative.

**Theorem 3.4.** For model (2.1) with $s$ species and $n$ patches,

$$R_0 = \rho(GB^{-1}CA^{-1})$$

If $R_0 < 1$, then the DFE is globally asymptotically stable, if $R_0 > 1$ then the DFE is unstable.

**Proof.** Due to the particular structure of $F$ and $V$, the computation of $\rho(FV^{-1})$ is greatly simplified. Indeed, the inverse $V^{-1}$ of $V$ keeps its block triangular structure

$$V^{-1} = \begin{bmatrix} A^{-1} & 0 \\ B^{-1}CA^{-1} & B^{-1} \end{bmatrix}$$

and

$$FV^{-1} = \begin{bmatrix} 0; G \\ 0; 0 \end{bmatrix} \begin{bmatrix} A^{-1} & 0 \\ B^{-1}CA^{-1} & B^{-1} \end{bmatrix} = \begin{bmatrix} GB^{-1}CA^{-1} & GB^{-1} \\ 0 & 0 \end{bmatrix}$$

Thus

$$R_0 = \rho(GB^{-1}CA^{-1})$$

Since $GB^{-1}CA^{-1}$ is a nonnegative matrix, its spectral radius is attained at the largest real eigenvalue. If $R_0 < 1$, then the DFE is locally stable, whereas if $R_0 > 1$, then the DFE is unstable [van den Driessche and Watmough, 2002, Theorem 2].
To establish the global stability of the DFE, consider the nonautonomous system consisting of (2.1c), (2.1d) and (2.1b) written in the form

$$\frac{dE_{ip}}{dt} = \sum_{j=1}^{n} \beta_{ijp} \left( N_{ip} - E_{ip} - I_{ip} - R_{ip} \right) \frac{I_{jp}}{N_{jp}}$$

$$- (d_{ip} + \varepsilon_{ip})E_{ip} + \sum_{q=1}^{n} m_{ipq} E_{iq} - \sum_{q=1}^{n} m_{ipq} E_{ip}$$

(3.2)

in which $S_{ip}$ has been replaced by $N_{ip} - E_{ip} - I_{ip} - R_{ip}$, and $N_{ip}$ is a solution of (2.2). Write this system as

$$x' = f(t, x)$$

(3.3)

where $x$ is the $3sn$ dimensional vector consisting of the $E_{ip}$, $I_{ip}$ and $R_{ip}$. The DFE of (2.1) corresponds to the equilibrium $x = 0$ in (3.3). System (2.2), i.e., (2.3) and (2.4), can be solved for $N_{ip}(t)$ independently of the epidemic variables, and Theorem 3.3 implies that the time dependent functions $N_{ip}(t) \to N_{ip}^*$ as $t \to \infty$. Substituting this large time limit value $N_{ip}^*$ for $N_{ip}$ in (3.2) gives

$$\frac{dE_{ip}}{dt} = \sum_{j=1}^{n} \beta_{ijp} \left( N_{ip}^* - E_{ip} - I_{ip} - R_{ip} \right) \frac{I_{jp}}{N_{jp}^*}$$

$$- (d_{ip} + \varepsilon_{ip})E_{ip} + \sum_{q=1}^{n} m_{ipq} E_{iq} - \sum_{q=1}^{n} m_{ipq} E_{ip}$$

(3.4)

Therefore, system (3.3) is asymptotically autonomous, with limit equation

$$x' = g(x)$$

(3.5)

To show that 0 is a globally asymptotically stable equilibrium for the limit system (3.5), consider the linear system

$$x' = Lx$$

(3.6)

where $x$ is the $3sn$ dimensional vector consisting of the $E_{ip}$, $I_{ip}$ and $R_{ip}$. In $L$, we replace $S_{ip}/N_{jp}$ with $N_{ip}^*/N_{jp}^*$. Equations (2.1c) and (2.1d) are not affected by this transformation, whereas (2.1b) takes the form

$$\frac{dE_{ip}}{dt} = \sum_{j=1}^{n} \beta_{ijp} \frac{N_{ip}^*}{N_{jp}^*} I_{jp} - (d_{ip} + \varepsilon_{ip})E_{ip} + \sum_{q=1}^{n} m_{ipq} E_{iq} - \sum_{q=1}^{n} m_{ipq} E_{ip}$$

(3.7)

Comparing (3.4) and (3.7), we note that $g(x) \leq Lx$ for all $x \in \mathbb{R}^{3sn}_+$. In system (3.6), the equations for $E_{ip}$ and $I_{ip}$ do not involve $R_{ip}$. Let $\tilde{x}$ be the part of the vector $x$ corresponding to the variables $E_{ip}$ and $I_{ip}$, and $\tilde{L}$ be the corresponding submatrix of $L$. The method of [van den Driessche and Watmough, 2002] as used to prove local stability can also be applied to study the stability of the $\tilde{x} = 0$ equilibrium of the subsystem $\tilde{x}' = \tilde{L}\tilde{x}$, with $\tilde{L} = F - V$. Therefore, if $R_0 < 1$, then
the equilibrium \( \bar{x} = 0 \) of the subsystem \( \bar{x}' = \bar{L}\bar{x} \) is stable. When \( \bar{x} = 0 \), (2.1d) takes the form

\[
\frac{dR_i}{dt} = (M_i - D_i)R_i
\]

with \( R_i = (R_{i1}, \ldots, R_{in})^t \) and \( D_i \) is the diagonal matrix with \( p \)th diagonal entry equal to \( d_{ip} \). It was shown in the proof of Theorem 3.3 that \( -M_i \) is a singular M-matrix. Using the result [Berman and Plemmons, 1979, A3 p. 149], it follows that \( -M_i + D_i \) is a nonsingular M-matrix for each \( D_i \). Thus the equilibrium \( \bar{x} = 0 \) of this linear system in \( \bar{x} \) is stable. As a consequence, the equilibrium \( x = 0 \) of (3.6) is stable when \( R_0 < 1 \). Using a standard comparison theorem (see, e.g., [Lakshmikantham et al., 1989, Theorem 1.5.4]), it follows that 0 is a globally asymptotically stable equilibrium of (3.5).

For \( R_0 < 1 \), the linear system (3.7) and (2.1c) has a unique equilibrium (the DFE) since its coefficient matrix \( F - V \) is nonsingular. The proof of global stability is completed using results on asymptotically autonomous equations; see, e.g., [Thieme, 1992, Thm. 4.1] and [Castillo-Chavez and Thieme, 1995].  

### 3.1 Example of three species on two patches

Consider a special case of 3 species on 2 patches, which could model, for example, the spread of bubonic plague between an urban area (patch 1) and the surrounding suburbs (patch 2), the species being fleas, rodents and humans. Likewise, the dynamics of many vector-borne diseases could be modeled this way.

For each species \( i = 1, 2, 3 \), the null vector of the mobility matrix \( M_i \) under the constraint of total population \( N_i^0 \) is

\[
(N_{11}^*, N_{12}^*) = \left( \frac{m_{i12}}{m_{i12} + m_{i21}} N_i^0, \frac{m_{i21}}{m_{i12} + m_{i21}} N_i^0 \right)
\]

The matrices \( G, A, B \) and \( C \) are as follows.

\[
G = \begin{bmatrix}
\beta_{111} & \beta_{121} \frac{S_{11}}{N_{11}} & \beta_{131} \frac{S_{11}}{N_{12}} \\
\beta_{211} \frac{S_{21}}{N_{11}} & \beta_{221} & \beta_{231} \frac{S_{21}}{N_{12}} \\
\beta_{311} \frac{S_{31}}{N_{11}} & \beta_{321} \frac{S_{31}}{N_{12}} & \beta_{331}
\end{bmatrix}
\]

\[
A = \begin{bmatrix}
0 & \beta_{112} \frac{S_{12}}{N_{12}} & \beta_{122} \frac{S_{12}}{N_{12}} & \beta_{132} \frac{S_{12}}{N_{12}} \\
\beta_{212} \frac{S_{22}}{N_{12}} & \beta_{222} & \beta_{232} \frac{S_{22}}{N_{12}} \\
\beta_{312} \frac{S_{32}}{N_{12}} & \beta_{322} \frac{S_{32}}{N_{12}} & \beta_{332}
\end{bmatrix}
\]

Let

\[
\tilde{M} = \begin{bmatrix}
-m_{121} & 0 & 0 & m_{112} & 0 & 0 \\
0 & -m_{221} & 0 & 0 & m_{212} & 0 \\
0 & 0 & -m_{321} & 0 & 0 & m_{312} \\
m_{121} & 0 & 0 & 0 & -m_{112} & 0 \\
m_{221} & 0 & 0 & 0 & -m_{212} & 0 \\
m_{321} & 0 & 0 & 0 & -m_{312} & 0
\end{bmatrix}
\]
Then

\[
A = \begin{bmatrix}
\begin{array}{cccc}
  d_{11} + \varepsilon_{11} & 0 & 0 & 0 \\
  0 & d_{21} + \varepsilon_{21} & 0 & 0 \\
  0 & 0 & d_{31} + \varepsilon_{31} & 0 \\
  0 & 0 & 0 & d_{41} + \varepsilon_{41}
\end{array}
\end{bmatrix} - \tilde{M}
\]

\[
B = \begin{bmatrix}
\begin{array}{cccc}
  d_{11} + \gamma_{11} & 0 & 0 & 0 \\
  0 & d_{21} + \gamma_{21} & 0 & 0 \\
  0 & 0 & d_{31} + \gamma_{31} & 0 \\
  0 & 0 & 0 & d_{41} + \gamma_{41}
\end{array}
\end{bmatrix} - \tilde{M}
\]

and \( C = \text{diag}(\varepsilon_{11}, \varepsilon_{21}, \varepsilon_{31}, \varepsilon_{12}, \varepsilon_{22}, \varepsilon_{32}) \).

To obtain \( R_0 \) for a given set of parameter values, we compute the spectral radius of the 6×6 matrix \( GB^{-1}CA^{-1} \) (see Theorem 3.4).

### 4 Case of one species

System (2.1), specialized to one species on \( n \) patches could model, for example, the spread of pneumonic plague, measles or smallpox between distinct cities or blocks within a single city. For convenience, drop the species index, thus \( \beta_p \) is the contact rate in patch \( p \).

**Theorem 4.1.** For model (2.1), in the case of one species on \( n \) patches,

\[
R_0 = \rho(\text{diag}(\beta_p)B^{-1}\text{diag}(\varepsilon_p)A^{-1})
\]

Furthermore, if \( R_0 < 1 \), then the DFE is globally asymptotically stable, if \( R_0 > 1 \), then the DFE is unstable.

**Proof.** In the notation of Section 3, \( G = \text{diag}(\beta_p) \), \( M \) is given by (2.4) with the species index \( i \) dropped, \( A = \text{diag}(d_p + \varepsilon_p) - M \), \( B = \text{diag}(d_p + \gamma_p) - M \) and \( C = \text{diag}(\varepsilon_p) \) where the matrices are \( n \times n \). Thus the results of Theorem 3.4 apply, with

\[
R_0 = \rho(\text{diag}(\beta_p)B^{-1}\text{diag}(\varepsilon_p)A^{-1})
\]

In the special case of isotropic mobility, i.e., \( m_{pq} = m > 0 \) for all \( p, q \neq p \), matrix \( M = -nmI_n + mJ_n \), where \( I_n \) is the \( n \times n \) identity matrix and \( J_n \) is the \( n \times n \) matrix of all ones. If, in addition, all parameters are equal in each patch, then the model behavior reduces to that of a one species SEIR epidemic model with no spatial dynamics.

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Theorem 4.2. Consider the case of model (2.1) with one species, isotropic mobility and equal parameters in each patch. Then $R_0 = \frac{\beta_p}{(d+\varepsilon)(d+\gamma)}$. For $R_0 < 1$, the DFE is globally asymptotically stable. For $R_0 > 1$, there is a unique endemic equilibrium $(S_p^*, E_p^*, I_p^*, R_p^*)$ given by $S_p^* = \frac{N_0^p}{nR_0}$, $I_p^* = \frac{\varepsilon d N_0}{n(d+\varepsilon)(d+\gamma)} (1 - \frac{1}{R_0})$, $E_p^* = \frac{d+\gamma}{\varepsilon} I_p^*$ and $R_p^* = \frac{\gamma}{\beta} I_p^*$ for $p = 1, \ldots, n$.

Proof. Since parameters are equal in each patch, let $\beta_p = \beta$, $\epsilon_p = \epsilon$, $\gamma_p = \gamma$ and $d_p = d$ for $p = 1, \ldots, n$. For isotropic mobility the matrices in the proof of Theorem 4.1 are $A = (d + \epsilon + nm)I_n - mJ_n$, $B = (d + \gamma + nm)I_n - mJ_n$ and $C = \epsilon I_n$. Since these matrices commute and the smallest eigenvalues of $A$ and $B$ are $(d + \epsilon)$ and $(d + \gamma)$, respectively, Theorem 4.1 gives $R_0 = \frac{\beta}{(d+\epsilon)(d+\gamma)}$ and global asymptotic stability when $R_0 < 1$. For $R_0 > 1$, system (2.1) can be solved to give the unique endemic equilibrium as stated so that $\sum_{p=1}^n N_p = N_0^p$.

Numerical simulations in the special case of Theorem 4.2 indicate that, if $R_0 > 1$, then solutions tend to this unique endemic equilibrium. Numerical simulations for the general case of one species and $n$ patches with $R_0$ as given by Theorem 4.1, indicate that for $R_0 > 1$ this model also tends to a unique endemic equilibrium with disease present in each patch (recall that $M$ is assumed to be irreducible).

4.1 Two patches case

In this case, the null vector of the mobility matrix $M$ is

$$(N_1^*, N_2^*) = \left( \frac{m_{12}}{m_{12} + m_{21}} N_0^0, \frac{m_{21}}{m_{12} + m_{21}} N_0^0 \right)$$

from Theorem 3.3. The basic reproduction number $R_0$ can then be obtained by Theorem 4.1 as the largest root of a quadratic equation.

The influence of small migration on the reproduction number can be found by neglecting terms of second order in $m_{pq}$. Provided parameter values are not all equal in the two patches, then small mobility can help to stabilize the DFE. Let $R_0^p = \frac{\beta_p \epsilon_p}{(d_p + \epsilon_p)(d_p + \gamma_p)}$ be the basic reproduction number in patch $p$.

Consider the case of model (2.1) with one species, two patches and small rates of travel, i.e., $m_{12}, m_{21} \ll 1$, with not all parameters equal in the two patches. Then $R_0$ is approximated by the spectral radius of $\text{diag}(h_1, h_2)/(\det A \det B)$ where

$$h_r = \beta_r \epsilon_r \prod_{p=1}^2 \left\{ (d_p + \epsilon_p + \sum_{q=1}^2 m_{pq})(d_p + \gamma_p + \sum_{q=1}^2 m_{pq}) \right\}.$$

But $(\det A \det B)$ is approximately equal to

$$\prod_{p=1}^2 \{(d_p + \epsilon_p + \sum_{q=1}^2 m_{pq})(d_p + \gamma_p + \sum_{q=1}^2 m_{pq})\}.$$
Neglecting terms in $m_{pq}^2$, this gives $R_0$ approximately equal to

$$\max_{p=1,2} \left\{ \frac{\beta_p \varepsilon_p}{(d_p + \varepsilon_p + \sum_{q=1}^{2} m_{qp})(d_p + \gamma_p + \sum_{q=1}^{2} m_{qp})} \right\}$$

$$= \max_{p=1,2} \left\{ \frac{R_0^p}{(1 - \sum_{q=1}^{2} m_{qp})} \left( \frac{1 - \sum_{q=1}^{2} m_{qp}}{d_p + \gamma_p} \right) \right\}$$

$$= \max_{p=1,2} \left\{ \frac{R_0^p}{(1 - \sum_{q=1}^{2} m_{qp})} \left( \frac{2d_p + \varepsilon_p + \gamma_p}{(d_p + \varepsilon_p)(d_p + \gamma_p)} \right) \right\} < \max_{p=1,2} R_0^p$$

by the irreducibility assumption.

To illustrate the above results, we have carried out numerical simulations for a single species on two spatial patches. We have chosen parameter values compatible with influenza, and such that $R_0^1$ is slightly larger than 1 and $R_0^2$ is slightly less than 1. Specifically, $1/\gamma_1 = 1/\gamma_2 = 2$ days, $1/d_1 = 1/d_2 = 77$ years, $1/\varepsilon_1 = 1/\varepsilon_2 = 4$ days. Using $\beta_1 = 0.5076$, $\beta_2 = 0.4761$ gives $R_0^1 = 1.015$ and $R_0^2 \approx 0.952$. The initial population in each patch is 20,000, with 19,950 susceptible and 50 infectious individuals. When there is no movement between patches, an endemic equilibrium is reached in patch 1, while in patch 2 the disease dies out (Fig. 1(a)). If mobility is introduced, but is sufficiently small, as in Fig. 1(b), where $m_{12} = m_{21} = 0.001$, $R_0$ is greater than 1 ($R_0 \approx 1.0095$ from Theorem 4.1) and the system approaches an endemic equilibrium in both patches. As mobility is increased, $R_0$ becomes less than 1 ($R_0 \approx 0.985$ from Theorem 4.1) and a disease free state is approached in both patches. This is illustrated in Fig. 1(c), in which $m_{12} = m_{21} = 0.05$.

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References


Figure 1: Effect of small migration on a two patch, one species system. The initial population is of 20000 individuals per patch, including 50 infectives. Parameters as in the text. Displayed are the infective fractions in each patch, $I_1/N_1$ and $I_2/N_2$, as functions of time. (a) No migration; (b) Very small migration ($m_{12} = m_{21} = 0.001$); (c) Small migration ($m_{12} = m_{21} = 0.05$).


